

# TPT-C

2+2 independent jaw movement  
Tongue & groove

## High precision 2+2 jaw power chuck with self-centering independent jaw movement Ø 210 - 400 mm

- closed center
- tongue & groove



### Application/customer benefits

- Clamping of rectangular and square workpieces, self-centering in two axes

### Technical features

- 2+2 jaw chuck with 2 independent self-centering jaw drives (two wedge drives)
- jaw No. 1 + 3 (clamping jaws): power operated
- jaw No. 2 + 4 (centering jaws): spring operated or optionally power operated
- chuck body and internal parts are case hardened for high precision and long life

### Standard equipment\*

2+2 jaw chuck  
Mounting bolts

### Ordering example

Power chuck TPT-C 250 A8 or  
TPT-C 400-Z

## A One wedge drive

- Operated by standard closed center cylinders.
- Jaws 2 and 4 are spring operated to center the component in one axis.
- Jaws 1 and 3 are power operated from the cylinder to center the component on the second axis and to apply the gripping force to drive the component.
- See specific draw pull, gripping force and maximum speed in the technical data table below.

## B Two independent wedge drives\*

- Operated by independent double piston cylinders.
- Jaws 2 and 4 are power operated (using the small cylinder) to center the component in one axis.
- Jaws 1 and 3 are also power operated (using the large cylinder) to center the component on the second axis and to apply the gripping force to drive the component.
- Since both pair of jaws are power operated the chuck can reach higher speeds.
- See specific draw pull, gripping force and maximum speed in the technical data table below.

\*Note: the chucks are always delivered as "one wedge drive" version: To use them as "two independent wedge drives" version, just remove the internal "spring assembly" according to instruction manual.

## Technical data

SMW-AUTOBLOK Type		TPT-C 210	TPT-C 250	TPT-C 315	TPT-C 400
Number of jaws		2+2	2+2	2+2	2+2
Radial jaw stroke	mm	4	5	5	7
Wedge stroke	mm	19	24	24	33
Weight (plain back without top jaws)	kg	21	32	48	102
Moment of inertia	kg·m <sup>2</sup>	0.12	0.27	0.64	1.95

## A ONE wedge drive

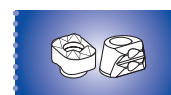
Max. draw pull* (clamping wedge, jaw 1 + 3)	kN	29	39	45	60
Max. gripping force jaw 1 + 3* (power operated)	kN	72	98	115	150
Max. centering force jaw 2 + 4 (spring operated)	kN	11	15	15	24
Max. speed	r.p.m.	2500	2400	2000	1500
Recommended actuating cylinders	type	SIN-S 125	SIN-S 125	SIN-S 150	SIN-S 150

## B TWO independent wedge drives

Max. draw pull* (clamping wedge, jaw 1 + 3)	kN	25	34	40	50
Max. draw pull* (centering wedge, jaw 2 + 4)	kN	19	25	30	35
Max. gripping force jaw 1 + 3* (power operated)	kN	72	98	115	150
Max. centering force jaw 2 + 4 (power operated)	kN	55	72	85	100
Max. speed	r.p.m.	4300	3400	2700	2000
Recommended actuating cylinders**	type	DCE 64/64	DCE 64/64	DCE 64/64	DCE 64/64

\* For internal clamping reduce the draw pull by 30 %

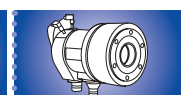
\*\* Technical details of DCE cylinders see page 238



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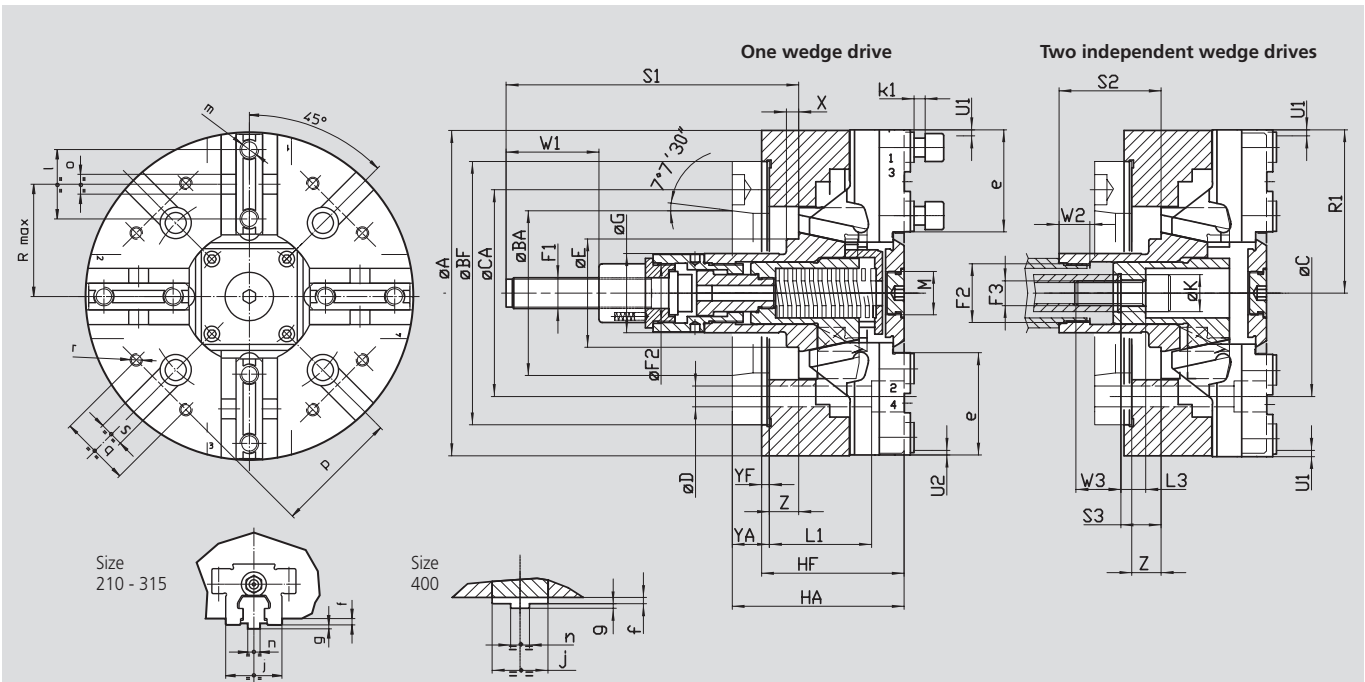
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Subject to technical changes  
For more detailed information please ask for customer drawing

SMW-AUTOBLOK Type			TPT-C 210		TPT-C 250			TPT-C 315			TPT-C 400	
Mounting			FL170	A6	FL220	A6*	A8	FL300	A8*	A11	FL300	A11
	<b>A</b>	mm	210		254			315			390	
	<b>Bf/BA H6</b>	mm	170	106.375	220	106.375	139.719	300	139.719	196.869	300	196.869
	<b>C</b>	mm	133.4		171.4		171.4		235		235	
	<b>CA</b>	mm	-	-	-	133.4	-	-	171.4	-	-	-
	<b>D</b>	mm	13.5		17		13.5		17		21	
	<b>E</b>	mm	70		88			110			98	
	<b>F1</b>	mm	M20		M24			M24			M24	
	<b>F2</b>	mm	M38 x 1.5		M56 x 2			M56 x 2			M56 x 2	
	<b>F3</b>	mm	M16		M20			M20			M20	
	<b>G</b>	mm	51		61			61			70	
Chuck height	<b>Hf/HA</b>	mm	92	111	105	124	127	111	127	136	116	140
	<b>K H8</b>	mm	24		30			30			35	
	<b>L1</b>	mm	66		59			33			54	
	<b>L3</b>	mm	11		9			11			11	
	<b>M</b>	mm	M28 x 1.5		M28 x 1.5			M28 x 1.5			M24 x 1	
	<b>R1</b>	mm	105.5		127.5			158			196	
	<b>Rmax</b>	mm	72		88			105			133.5	
	<b>S1</b>	mm	189		203			201			218	
	<b>S2</b>	mm	61		71			69			86	
	<b>S3</b>	mm	21		33			31			45.5	
Jaw stroke (power 1 + 3)	<b>U1</b>	mm	4		5			5			7	
Jaw stroke (spring 2 + 4)	<b>U2</b>	mm	3		4			4			5.4	
	<b>W1</b>	mm	60		60			60			60	
	<b>W2</b>	mm	20		20			20			20	
	<b>W3</b>	mm	29		31			29			29	
	<b>X</b>	mm	8		8			10			10	
	<b>Yf/YA</b>	mm	5	24	5	24	27	5	30	30	6	30
Wedge stroke	<b>Z</b>	mm	19		24			24			33	
	<b>e</b>	mm	66		77.5			93			116	
	<b>f</b>	mm	4		4			4			7	
	<b>g</b>	mm	2.5		3			3			3	
	<b>j</b>	mm	36		45			45			62	
	<b>k1</b>	mm	11		12			12			14	
	<b>l</b>	mm	44.4		54			54			76.2	
	<b>m</b>	mm	M12		M16			M16			M20	
	<b>n h8</b>	mm	7.94		12.7			12.7			12.7	
	<b>o H7</b>	mm	12.68		19.03			19.03			19.03	
	<b>p</b>	mm	80		102			100			150	
	<b>q</b>	mm	45		60			60			80	
	<b>r</b>	mm	M8		M10			M10			M12	
	<b>s H8</b>	mm	16		16			20			20	
	<b>t</b>	mm	5		5			5			5	

\* Indirect mounting